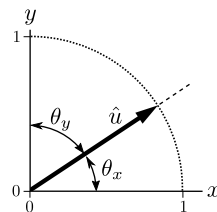


$$\vec{A} = \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k} = A \hat{u} \quad \hat{u} = \frac{\vec{A}}{A} \quad c\vec{A} + d\vec{B} = \begin{bmatrix} cA_x + dB_x \\ cA_y + dB_y \\ cA_z + dB_z \end{bmatrix}$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z = AB \cos \theta$$

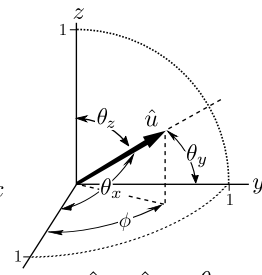
$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

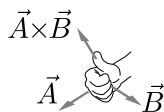


$$\sin \theta_x = \cos \theta_y$$

$$\hat{u} = \hat{i} \cos \theta_x + \hat{j} \sin \theta_x$$

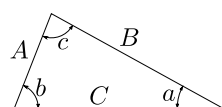


$$\hat{u} = \hat{i} \cos \theta_x + \hat{j} \cos \theta_y + \hat{k} \cos \theta_z$$



$$\vec{A} \times \vec{B} = (AB \sin \theta) \hat{u}_\perp$$

$$\vec{A} \times \vec{B} = (A_y B_z - A_z B_y) \hat{i} + (A_z B_x - A_x B_z) \hat{j} + (A_x B_y - A_y B_x) \hat{k}$$



$$C^2 = A^2 + B^2 - 2AB \cos c$$

$$\frac{A}{\sin a} = \frac{B}{\sin b} = \frac{C}{\sin c}$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\cos^2 \theta + \sin^2 \theta = 1$$

useful approximations:

if $|x| \ll 1$ then
 $(1+x)^\alpha \approx 1 + \alpha x$

if $\theta \ll 1$ then
 $\sin \theta \approx \theta$
 $\tan \theta \approx \theta$
 $\cos \theta \approx 1$

$$\vec{F}_{\text{net}} = m\vec{a} = \frac{d\vec{p}}{dt}$$

$$\vec{F}_G = m\vec{g}$$

$$K = \frac{1}{2}mv^2$$

$$W = \vec{F} \cdot \vec{s}$$

$$F_{\text{centrip}} = m\omega^2 r$$

$$\vec{F}_{12} = -\vec{F}_{21}$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$$

$$\vec{v} = \frac{d}{dt}\vec{r}(t)$$

$$\vec{a} = \frac{d}{dt}\vec{v}(t)$$

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \hat{r}$$

$$k = \frac{1}{4\pi\epsilon_0}$$

$$\vec{F} = q\vec{E}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{2\lambda}{r} \hat{r}$$

$$\vec{E} = \frac{\sigma}{2\epsilon_0} \hat{n}$$

$$\vec{E} = \frac{\sigma}{\epsilon_0} \hat{n}$$

$$\vec{p} = q\vec{s}$$

$$\Phi_e = \vec{E} \cdot \vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{in}}}{\epsilon_0}$$

$$V = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$$

$$U = qV$$

$$\vec{\tau} = \vec{p} \times \vec{E}$$

$$\vec{E}_{\text{dp}} = \frac{1}{4\pi\epsilon_0} \frac{2\vec{p}}{r^3}$$

$$E_s = -\frac{dV}{ds}$$

$$\Delta V = -\int_i^f E_s ds$$

$$C = \frac{Q}{V_C}$$

$$C = \kappa C_0$$

$$C_{\text{pp}} = \epsilon_0 \frac{A}{d}$$

$$U_{\text{dp}} = -\vec{p} \cdot \vec{E}$$

$$U = \frac{QV_C}{2} = \frac{CV_C^2}{2} = \frac{Q^2}{2C}$$

$$u_e = \frac{1}{2} \kappa \epsilon_0 E^2$$

$$I = \frac{dq}{dt}$$

$$J = \frac{I}{A}$$

$$J = \sigma E$$

$$\sigma = \rho^{-1}$$

$$R = \frac{\rho L}{A}$$

$$V = IR$$

$$I = n_e e A v_d$$

$$P = IV = \frac{V^2}{R} = I^2 R$$

$$\tau = RC$$


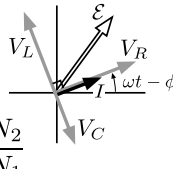
$$X(t) = X_0 e^{-t/\tau}$$

$$X(t) = X_0 (1 - e^{-t/\tau})$$

around a circuit loop: $\sum \Delta V_i = 0$

at a circuit junction: $\sum I_{\text{in}} = \sum I_{\text{out}}$

Series	Parallel
$\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$	$C_T = C_1 + C_2 + C_3 + \dots$
$V_T = V_1 + V_2 + V_3 + \dots$	$V_1 = V_2 = V_3 = \dots$
$I_1 = I_2 = I_3 = \dots$	$I_T = I_1 + I_2 + I_3 + \dots$
$R_T = R_1 + R_2 + R_3 + \dots$	$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$

Magnetism	$\vec{F} = q\vec{v} \times \vec{B}$ $\vec{F} = I\vec{\ell} \times \vec{B}$ $\vec{\mu} = NIA\hat{n}$ $\vec{\tau} = \vec{\mu} \times \vec{B}$ $r_{\text{cyc}} = \frac{mv}{qB}$		
	$\vec{B} = \frac{\mu_0 q\vec{v} \times \hat{r}}{4\pi r^2}$ $d\vec{B} = \frac{\mu_0 Id\vec{\ell} \times \hat{r}}{4\pi r^2}$ $B_{\text{wire}} = \frac{\mu_0 I}{2\pi r}$ 		
Induction	$B_{\text{loop}} = \frac{\mu_0 I}{2R}$ $B_{\text{sol}} = \frac{\mu_0 NI}{\ell}$ $F = \frac{\mu_0 I_1 I_2}{2\pi r} \ell$ $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{\text{thru}}$		
	$\mathcal{E} = v\ell B$ $\mathcal{E} = NBA\omega \sin(\omega t)$ $\Phi_m = \int_{\text{area}} \vec{B} \cdot d\vec{A}$ $\mathcal{E}_1 = -M \frac{dI_2}{dt}$		
	$M = \frac{N_2 \Phi_2}{I_1} = \frac{N_1 \Phi_1}{I_2}$ $L = N \frac{\Phi_m}{I}$ $\mathcal{E} = -L \frac{dI}{dt}$		
AC Circuits	$\mathcal{E} = \oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_m}{dt}$ $L_{\text{sol}} = \frac{\mu_0 N^2 A}{\ell}$ $U_L = \frac{1}{2} LI^2$ $u_B = \frac{1}{2\mu_0} B^2$		
	$V_L(t) = V_0 e^{-t/\tau}$ $\tau = L/R$ $V_L(t) = V_0 \cos(\omega t + \phi)$ $\omega = \frac{1}{\sqrt{LC}}$		
	$\mathcal{E}(t) = \mathcal{E}_0 \cos \omega t$ $i(t) = I \cos(\omega t - \phi)$ $X_C = 1/\omega C$ $X_L = \omega L$		
	$\omega = 2\pi f = \frac{2\pi}{T}$ $V_R = IR$ $V_C = IX_C$ $V_L = IX_L$ $\mathcal{E}_0 = IZ$		
EM Waves	$V_{\text{rms}} = \frac{V}{\sqrt{2}}$ $I_{\text{rms}} = \frac{I}{\sqrt{2}}$ $P_R = I_{\text{rms}} V_{\text{rms}}$ $\mathcal{E}_0^2 = V_R^2 + (V_L - V_C)^2$		
	$\phi = \tan^{-1} \frac{X_L - X_C}{R}$ $Z = \sqrt{R^2 + (X_L - X_C)^2}$ 		
	$\omega_c = \frac{1}{RC}$ $\omega_0 = \frac{1}{\sqrt{LC}}$ $P = I_{\text{rms}} \mathcal{E}_{\text{rms}} \cos \phi$ $\frac{V_2}{V_1} = \frac{N_2}{N_1}$		
	$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{in}}}{\epsilon_0}$ $\oint \vec{B} \cdot d\vec{A} = 0$ $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$		
Optics	$\oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_m}{dt}$ $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{\text{thru}} + \epsilon_0 \mu_0 \frac{d\Phi_e}{dt}$ $c = f\lambda$		
	$c^2 = \frac{1}{\epsilon_0 \mu_0}$ $\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$ $\frac{E_0}{B_0} = c$		
	$I = S_{\text{ave}} = \frac{E_0 B_0}{2\mu_0}$ $I = \frac{P_{\text{source}}}{4\pi r^2}$ $I = I_0 \cos^2 \theta$		
$\frac{1}{d_o} + \frac{1}{d_i} = \frac{1}{f}$ $f = \frac{R}{2}$ $n = \frac{c}{v}$ $m = -\frac{d_i}{d_o} = \frac{h_i}{h_o}$ $\sin \theta_c = \frac{n_2}{n_1}$			
$\frac{n_1}{n_2} = \frac{v_2}{v_1} = \frac{\lambda_2}{\lambda_1} = \frac{\sin \theta_2}{\sin \theta_1}$ $M = \frac{\theta_i}{\theta_o}$ $\frac{1}{f} = (n-1) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$			
$d \sin \theta = m\lambda$ $a \sin \theta = m\lambda$ $I = I_0 \left(\frac{\sin(\phi/2)}{\phi/2} \right)^2$ $\phi = 2\pi \frac{a \sin \theta}{\lambda}$			
$D \sin \theta = 1.22\lambda$			

Constants	Coulomb constant	k	$8.99 \times 10^9 \text{ N m}^2/\text{C}^2$
	electron mass	m_e	$9.11 \times 10^{-31} \text{ kg}$
	fundamental charge	e	$1.60 \times 10^{-19} \text{ C}$
	permittivity of free space	ϵ_0	$8.854 \times 10^{-12} \text{ F/m}$
	permeability of free space	μ_0	$4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}$
	speed of light	c	$3.00 \times 10^8 \text{ m/s}$

Symbols and Units	area	A	m^2
	acceleration	a	m/s^2
	slit width	a	m
	magnetic field	B	T
	capacitance	C	F
	distance	d	m
	slit separation	d	m
	diameter	D	m
	slit width	D	m
	electric field	E	V/m, N/C
	emf	\mathcal{E}	V
	frequency	f	$1/\text{s, Hz}$
	focal length	f	m
	force	F	N
	image, object size	h_i, h_o	m
	current	I, i	A, C/s
	intensity	I	W/m^2
	current density	J	C/s/m^2
	Coulomb constant	k	$\text{N m}^2/\text{C}^2$
	kinetic energy	K	J
	length	ℓ, l	m
	inductance	L	$\text{H, T}\cdot\text{m}^2/\text{A}$
	mass	m	kg
	order	m	(none)
	lateral magnification	m	(none)
	mutual inductance	M	$\text{H, T}\cdot\text{m}^2/\text{A}$
	angular magnification	M	(none)
	number	N	(none)
	unit normal vector	\hat{n}	(none)
	number density	n	m^{-3}
	refractive index	n	(none)
	electric dipole moment	p	$\text{C}\cdot\text{m}$
	power	P	W, J/s
	electric charge	q, Q	C
	unit radial vector	\hat{r}	(none)
	distance or radius	r, R	m
	resistance	R	Ω
	path length	s	m
	image, object distance	d_i, d_o	m
	Poynting vector	S	W/m^2
	time	t	s
	potential energy	U	J
energy density	u	J/m^3	
unit vector	\hat{u}	(none)	
velocity	v	m/s	
electric potential	V	V	
work	W	$\text{J, N}\cdot\text{m}$	
reactance	X	Ω	
x, y -axis coordinate	x, y	m	
impedance	Z	Ω	
angle	θ	radians	
dielectric constant	κ	(none)	
line charge density	λ	C/m	
wavelength	λ	m	
magnetic moment	μ	$\text{A}\cdot\text{m}^2$	
resistivity	ρ	$\Omega\cdot\text{m}$	
conductivity	σ	$(\Omega\cdot\text{m})^{-1}$	
surface charge density	σ	C/m^2	
torque	τ	$\text{N}\cdot\text{m}$	
time constant	τ	s	
phase angle	ϕ	radians	
electric field flux	Φ_e	$\text{N}\cdot\text{m}^2/\text{C}$	
magnetic field flux	Φ_m	$\text{Wb, T}\cdot\text{m}^2$	
angular frequency	ω	rad/s	